

研究报告

2023 1 122 2023 03 6

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1-4			6
1-5			11
1-6	Pacifica		12
1-7	Zoox		13
1-8			14
1-9			17
2-1			18
2-2			20
2-3			28
3-1			31
1-1	DARPA		7
4-1			35
4-2	AI		37
4-3			39



Automated Vehicle Intelligent Vehicle

Autonomous Vehicle Self-driving Car Driverless Car

M

2014

Society of

Automotive Engineers International SAE International

1-1

Level 0

Level 5

6

[1]

Level 0

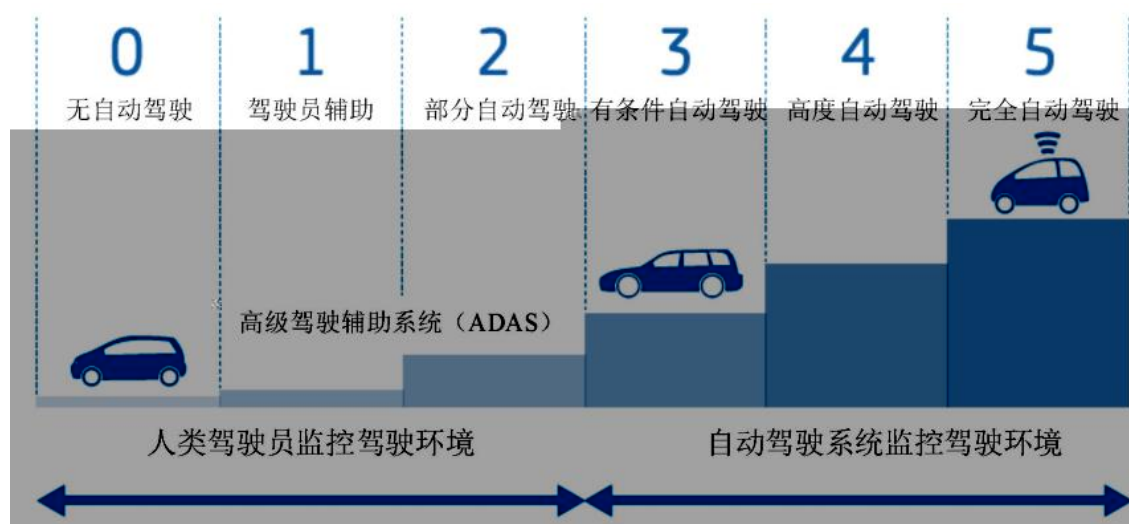
Level 1

Level 2

Level 3

Level 4

Level 5





Level 4

Level 5

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1-2

[2]

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5G

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ADAS

L1-L3

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Momenta

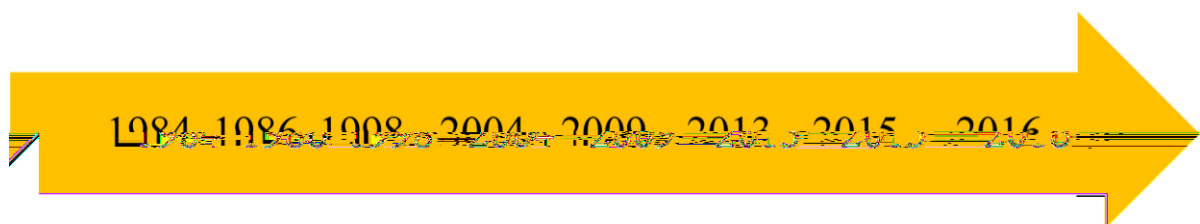
L4

L5

20

70

1-4





- NavLab-1 20 80
Sun3 GPS Warp

28km/h

- NavLab-5 1995 . Assist-
Ware Portable
Advanced Navigation Support PANS
I/O

SPARC Lx

NavLab-5

88.5km/h

Navlab-5

4496km

98.1%

- NavLab-11 Wrangler

102km/h

VisLab

ARGO

1998

ARGO

2000km

94%

112km/h

2010

ARGO



GPS

2013

2013

2018

Level 3

1

60km/h

[4]

Autopilot

7



Autopilot 1.0 2.0 2.5

OTA

Level 2

Level 4+

10

"FSD Beta"

"Tesla Vision"

2016

Cruise

Automation

2013

2018 1

Cruise Automation

—Cruise AV Cruise AV

21

16

5

Cruise AV

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SAE Level 4+



2009

Sebastian Thrun

Sebastian Thrun

Stanley

2005

DARPA

2012

2015



2016 12

—Waymo

2017

10

Google Waymo

Chandler 100

600

Level 4

Waymo

2018 5 31

Waymo

Fiat

Chrysler Automobiles FCA

62000

Pacifica

Waymo

FCA



“ ” SAE Level 4+

nuTonomy 2013

2016 8

nuTonomy

6

2

2017 10

nuTonomy^[5]

Zoox

3.6

Zoox

Zoox

2013

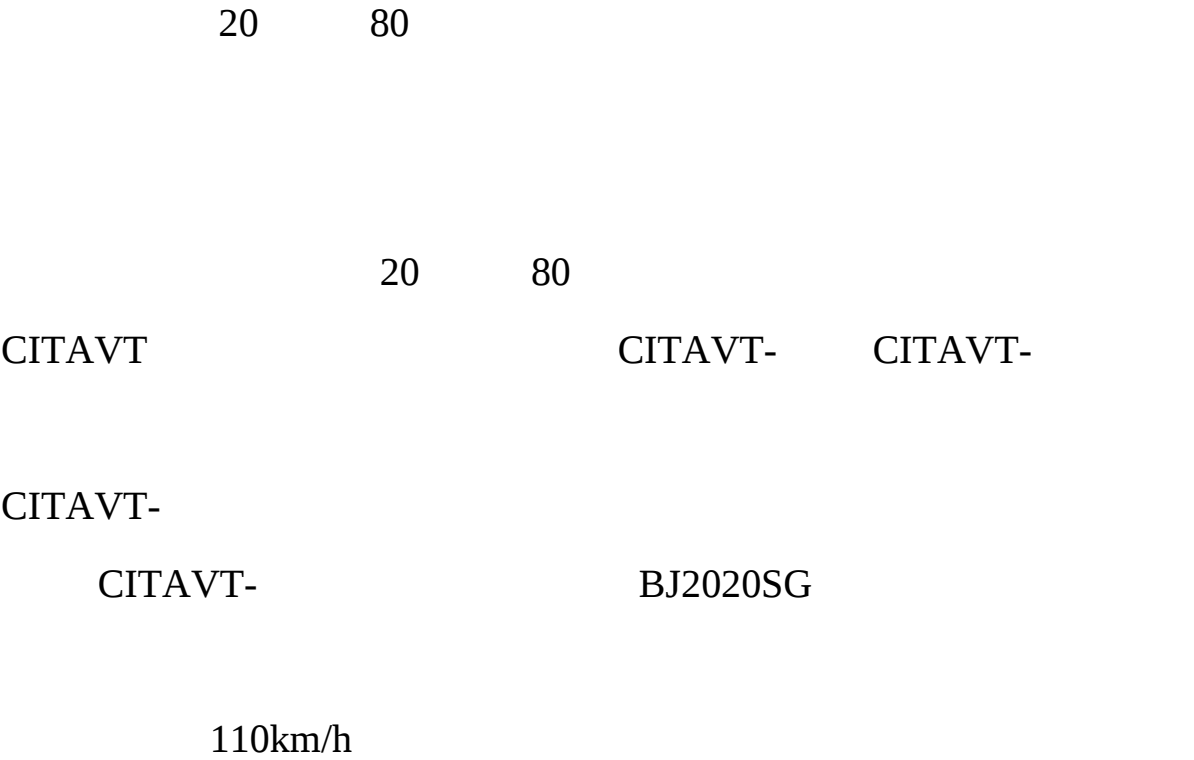
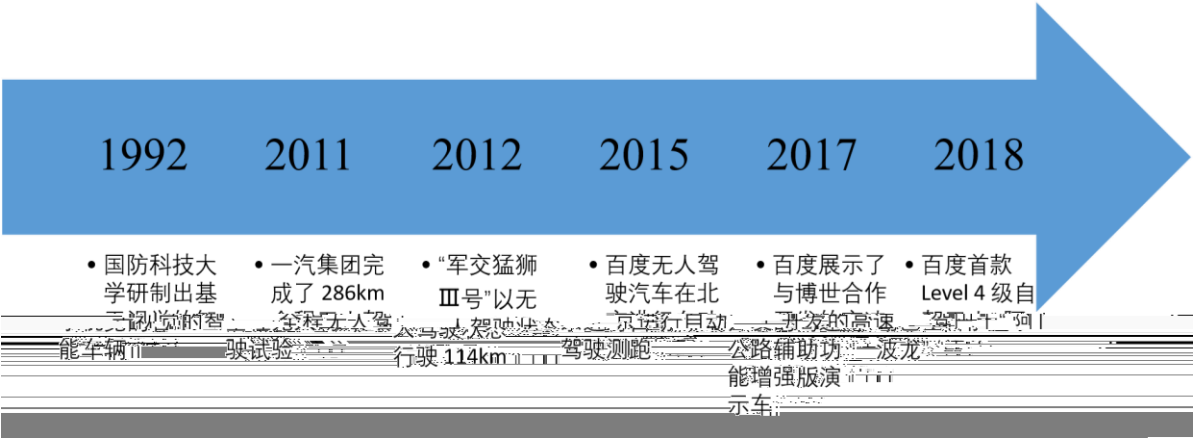
IEEE

1-7



90

1-8



1992



863

1988

THMR

THMR-

150km/h THMR-

20ms

2007

2011 7

HQ3

286km

0.78 2015 4

“ ”

2015 4 19

“ ”

2012

“ ”

114km

105km/h

5

3

1

GPS

2015 4

“ 654 ”

2015 8

32.6km

68km/h

2018 5

2018

Level 4

2016 4

EU260

GPS

2013

“

”



“ ”

2015 12

100km/h 2015 12 14

2017 4 17

2018 7 4

AI

Baidu Create 2018

Level

4 “ ” 1-9

100

2019

SB Drive

10 “

”

3.0

Safety	RSS
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[illegible]

[6]

2-1

[7]

V2X

5G

[8]

[9]



Convolutional Neural Networks CNN

Recurrent Neural Network RNN

Long Short

Term Memory LSTM

Deep Belief Network

DBN

Autoencoder, AE

5

2-2

4

10

à °



Once

RNN

RNN

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 “ + ”
 “ + ”
 ” Waymo Apollo Uber
 “ + ”

10

Simultaneous Localization
 and Mapping SLAM
 Artificial Neural Networks ANN



SLAM

CNN

CNN

CNN

CNN

SLAM

3D

SLAM

SLAM

Reinforcement Learning RL

SLAM

SLAM

[8]

[10]

Mobileye

Mobileye

2-3

[11]



[12]

[12]

(Artificial Intelligence

AI)

AI

RL

AI

RL

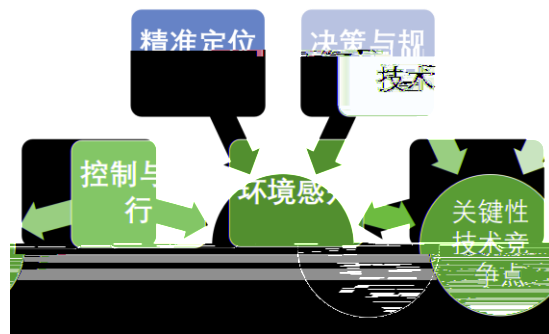


RL

RL

RL AI

RL



3-1

AI

AI

AI

AI

AI

“ ”

Velodyne	Quanergy		Liminar		
Innoviz	4	8	16	32	64

3

System ADAS

510

Alphabet



L4~L5

2020

Waymo

Waymo

Robotaxi

Waymo

Waymo

4-1

Waymo				Waymo Waymo
Cruise				Waymo Cruise Waymo Cruise L5 Waymo 2020 Cruise Waymo

Mobileye		L2		Mobileye SuperVision EyeQ5 L2+ L2 11 2
				L2-L5 Constellation OS Drive IX Xpilot Drive Driveworks Drive AV
Luminar				1550nm 2022 Sentinel Iris
Apollo				2013 2015 Apollo Waymo + + L5
				+ + 5G L5

4-2

AI

Waymo	2009	Waymo 3 55 2021 6 16 2021 6 16 25 2020 5 12 7.5 2020 3 2 23 * https://www.crunchbase.com/organization/waymo/company_financials
Cruise	2013	Cruise 13 151 2022 3 18 2022 3 18 -Cruise 21 2022 3 18 -Cruise 14 2021 6 15 -Cruise 50 * https://www.crunchbase.com/organization/cruise/company_financials
Mobileye	1999	Mobileye 5 5.15 2014 8 4 IPO 2014 8 4 IPO - Mobileye 2013 7 7 - Mobileye 4

4-3

	”
	“ ” “ “ DSA1250 “ X ”
	2000 75.6km/h 2003 6 CA7460 130km 170km 2006 8 HQ3 9 2007 3 “ — ” 2011 7 14 HQ3 2017 3 6



L4

ADAS

L2

L2

L4

2025

Artificial Intelligence AI

Artificial Neural Network ANN

Autonomous Land Vehicle ALV

Convolutional Neural Network CNN



()

Self-driving Autonomous vehicle, SdA

Simultaneous Localization and Mapping

SLAM

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-based autonomous vehicle recognition: A new challenge for deep learning-
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-based deep learning approach for fault diagnosis of an industrial autonomous



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vehicle ser

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Waymo Cruise

Mobileye Luminar

